

# THE BMC ENGINEERING COMPANION

TONY CRIPPS

# Contents

<b>CHAPTER 1. PRODUCTION &amp; IDENTIFICATION .....</b>	<b>10</b>
1.1 BMC Australia Product Engineering Documentation.....	10
1.1.1 Sketch .....	10
1.1.2 Part Numbers .....	11
1.1.3 Registers .....	13
1.1.4 Product Engineering Documents.....	14
1.2 Vehicle Identification .....	17
1.2.1 Introduction .....	17
1.2.2 Sheet Metal and Body Division Stampings.....	18
1.2.3 Terminology .....	18
1.2.4 Vehicle Identification .....	18
1.2.5 Compliance Plates .....	20
1.2.6 Date of Manufacture .....	21
1.2.7 Plate Attachment .....	21
1.2.8 The BMC-A Type Code.....	22
1.2.9 The Leyland Australia 10 Digit Code.....	22
1.2.10 The Leyland UK 8 Digit Code .....	24
1.3 Power Unit Identification.....	24
1.3.1 Introduction .....	24
1.3.2 BMC-A Power Unit Coding .....	25
1.3.3 Australian 4 Digit Prefix Code.....	26
1.3.4 British Leyland UK Code .....	27
1.4 Vehicle Identification Standards .....	28
1.4.1 Introduction .....	28
1.4.2 Engineering Standards (Australia).....	28
1.4.3 Engineering Technical Data .....	28
1.4.4 Standard Procedure Instructions .....	28
1.4.5 Service Documentation .....	29
1.4.6 UK Standards .....	29
1.5 Production Numbers.....	29
1.5.1 Introduction .....	29
1.5.2 Mini .....	29
1.5.3 YDO30 Californian Moke .....	32
1.5.4 The Galvanised Moke .....	40
<b>CHAPTER 2. POWER UNIT.....</b>	<b>42</b>
2.1 Introduction .....	42
2.1.1 The Mechanics of Machines.....	42
2.1.2 Equations of Motion.....	43
2.1.3 Indicated Power .....	46
2.1.4 Brake Power .....	48
2.2 Efficiency .....	48
2.2.1 Thermal Efficiency .....	48
2.2.2 Octane Rating.....	49
2.2.3 Volumetric Efficiency.....	50

2.2.4 Mechanical Efficiency .....	52
2.3 Combustion Chamber .....	52
2.4 Engine Vibrations .....	54
2.4.1 Turning Moment .....	54
2.4.2 Balance .....	57
2.4.3 Engine Mountings .....	58
2.5 Camshaft .....	59
2.5.1 Introduction .....	59
2.5.2 Follower Motion.....	60
2.5.3 Cam Profiles .....	63
2.6 Clutch .....	65
2.6.1 Clutch Performance .....	65
2.6.2 Clutch Release Bearing.....	68
2.7 Transmission .....	69
2.7.1 Introduction .....	69
2.7.2 Engine Speed Ratio .....	70
2.7.3 Gear Ratios.....	70
2.8 Vehicle Performance .....	73
2.8.1 Introduction .....	73
2.8.2 Engine Power Curve .....	73
2.8.3 Tractive Effort .....	74
2.8.4 Air Resistance and Rolling Resistance.....	76
2.8.5 Grade Resistance .....	77
2.8.6 Performance Curves YD05.....	78
2.8.7 Vehicle Acceleration .....	80
<b>CHAPTER 3. EMISSION CONTROL .....</b>	<b>89</b>
3.1 Emission Control .....	89
3.1.1 Introduction .....	89
3.1.2 Intake Air Temperature Control.....	91
3.1.3 Carburetter .....	92
3.1.4 Air Injection .....	92
3.1.5 Evaporative Loss Control (ELC) .....	94
3.2 Emission Control Testing .....	95
<b>CHAPTER 4. IGNITION SYSTEM.....</b>	<b>97</b>
4.1 Introduction .....	97
4.2 The Ignition Coil .....	97
4.2.1 Faraday's Law .....	98
4.2.2 Generating a High Voltage .....	99
4.2.3 Ballast Resistor .....	101
4.2.4 Condenser .....	102
4.2.5 Coil .....	102
4.2.6 Contact breaker .....	102
4.2.7 Electronic ignition .....	102
4.3 Spark Plug .....	103
4.3.1 Spark Plug Details.....	103
4.3.2 Spark Plug Testing .....	106
4.4 Ignition Advance .....	106
4.5 Distributor Testing .....	108

<b>CHAPTER 5. COOLING SYSTEM .....</b>	<b>114</b>
5.1 Introduction .....	114
5.2 Radiator.....	114
5.2.1 Radiator Function .....	114
5.2.2 Radiators .....	116
5.3 Radiator Cap.....	119
5.3.1 Pressurized Cooling .....	119
5.3.2 Radiator Caps .....	120
5.4 Fan Belt .....	121
5.4.1 Belt Transmission .....	121
5.4.2 Morris Mini Range.....	123
5.5 Thermostat.....	125
5.5.1 Need for a Thermostat.....	125
5.5.2 Thermostat Design .....	125
<b>CHAPTER 6. FUEL SYSTEM .....</b>	<b>127</b>
6.1 Fluid Dynamics .....	127
6.2 Combustion .....	130
6.3 The SU Carburetter .....	131
6.3.1 Introduction .....	131
6.3.2 Dashpot .....	133
6.3.3 Needle .....	134
6.4 Detonation .....	135
<b>CHAPTER 7. SUSPENSION .....</b>	<b>136</b>
7.1 Suspension Geometry .....	136
7.1.1 The Reason for a Suspension System.....	136
7.1.2 Roll Centres .....	136
7.1.3 Vehicle Mass.....	141
7.1.4 Suspension Springs.....	143
7.2 Hydrolastic Displacers .....	147
7.2.1 Introduction .....	147
7.2.2 ADO16 Morris 1100.....	148
7.2.3 YDO5/YDO22 Morris Mini .....	148
7.2.4 YDO6/YDO23 Morris Cooper S, Morris Mini Clubman GT .....	148
7.2.5 ADO17/YDO13/YDO19 Austin 1800, Austin Tasman/Kimberley .....	148
7.2.6 Hose Data .....	149
7.3 The Hydrolastic System.....	149
7.3.1 Hydrolastic Fluid.....	149
7.3.2 Charging the Hydrolastic Suspension.....	150
7.3.3 Ride Height .....	151
7.3.4 The Viscosity of Hydrolastic Fluid.....	152
7.4 Secret Life of a Tyre.....	154
<b>CHAPTER 8. STEERING .....</b>	<b>157</b>
8.1 The Ackerman Principle .....	157
8.1.1 Rolling Motion.....	157
8.1.2 Perfect Turning.....	158
8.1.3 Four-Link Ackerman Geometry .....	159
8.1.3 Rack and Pinion .....	161
8.1.4 Graphical Methods.....	163

8.1.5 Perfect Turning: Morris Mini.....	164
8.1.6 Perfect Turning Austin 1800 .....	168
8.2 Steering Racks (Mini range).....	169
8.3 Steering Arms .....	173
<b>CHAPTER 9. BRAKES .....</b>	<b>177</b>
9.1 The Theory of Braking.....	177
9.1.1 Introduction .....	177
9.1.2 Load Distribution.....	177
9.1.3 Drum Brakes.....	181
9.1.4 Master and Slave Cylinders.....	183
9.1.5 Braking Power .....	184
9.1.6 Stopping Distance .....	185
9.2 Morris 850 ADO15 .....	186
9.2.1 Foot brake .....	186
9.2.2 Handbrake.....	188
9.2.3 Rear Brake Pressure Limiting Valve .....	189
<b>CHAPTER 10. ELECTRICAL.....</b>	<b>190</b>
10.1 Voltage and Current.....	190
10.2 Battery .....	190
10.3 Starter Motor and Generator .....	193
10.3.1 Electromagnetic Induction.....	193
10.3.2 Generator Output Regulation .....	195
10.3.3 Alternator.....	196
10.4 Starter Motors .....	197
10.5 Wipers.....	201
10.6 The Lucas Windtone Horn .....	203
10.6.2 Minor Adjustment.....	207
10.6.3 Major Adjustment.....	208
10.6.4 Applications.....	208
10.7 The Astor Diamond Dot Car Radio.....	209
10.7.1 Introduction .....	209
10.7.2 Radio Frequency Receiver.....	210
10.7.3 Oscillator and Mixer.....	211
10.7.4 IF Amplifier .....	212
10.7.5 Audio Amplifier .....	213
10.7.6 Speaker Transformer .....	214
10.7.7 Fault Finding.....	215
10.7.8 Replacement Parts.....	221
10.7 Radio Interference Suppression. ....	222
10.8 Wiring and Fuses.....	222
10.8.1 Wiring Harness.....	222
10.8.2 Fuses .....	223
<b>CHAPTER 11. BODY.....</b>	<b>225</b>
11.1 Body Engineering.....	225
11.1.1 Introduction .....	225
11.1.2 Volume.....	227
11.1.3 Strength .....	230
11.2 Styling .....	232

11.3 Rust .....	235
11.3.1 Chemical Reaction .....	235
11.3.2 Rust and Corrosion .....	236
<b>CHAPTER 12. LIGHTING &amp; MIRRORS .....</b>	<b>238</b>
12.1 Introduction .....	238
12.2. Reflection and Refraction .....	238
12.2.1 Reflection .....	238
12.2.2 Refraction .....	239
12.2.3 Mirrors.....	240
12.2.4 Lenses .....	241
12.3. Headlamps .....	243
12,4 Interior Mirrors .....	244
<b>Appendix .....</b>	<b>249</b>

between 1<sup>st</sup> and 2<sup>nd</sup>, the engine rpm (in the newly selected gear) may fall below that of maximum torque if, perhaps, there is a significant grade being negotiated during a down change.

Since we know that the manufacturer has given bottom gear a ratio of 3.53 (1098cc) and 3.2 (1275cc), we can compute the expected geometrical ratio:

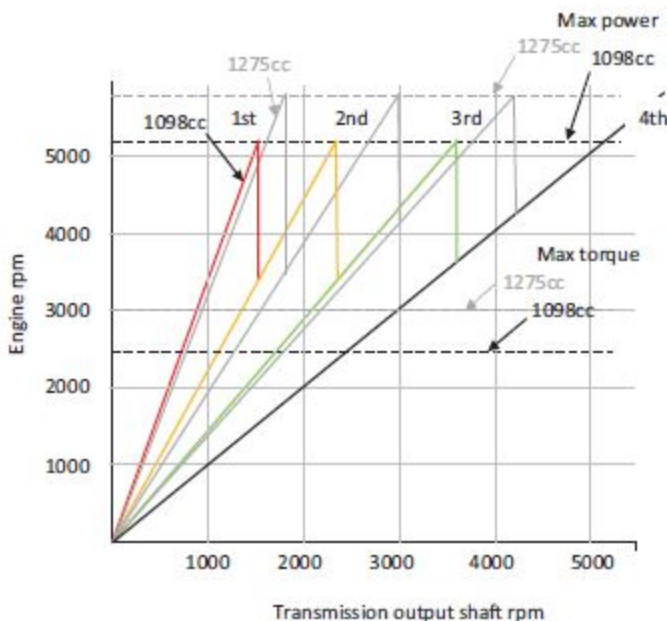
$$g = \frac{1}{\sqrt[3]{3.53}} = 0.657 \text{ and } g = \frac{1}{\sqrt[3]{3.2}} = 0.678$$

For a geometric progression,  $s_1 = k$ ,  $s_2 = kg$ ,  $s_3 = kg^2$  and  $s_4 = kg^3$ , we thus have a comparison in gear ratios:

	1098cc		1275cc	
$k$	3.53		3.2	
$g$	0.657		0.679	
	Theoretical	Actual	Theoretical	Actual
$s_1$	3.53	3.53	3.2	3.2
$s_2$	2.318	2.22	2.171	1.92
$s_3$	1.522	1.43	1.473	1.36
$s_4$	1	1	1	1

**Table 2.7.3** Comparison of geometrical gear ratios with factory specified gear ratios.

These data show that the gear spacing chosen by BMC are not quite in a geometric progression. A graph of engine rpm (gearbox input) vs gearbox output rpm illustrates the significance of the gear ratios.



**Fig. 2.7.1** Gearbox ratio characteristics for 1098cc (heavy lines) and 1275cc (light lines).



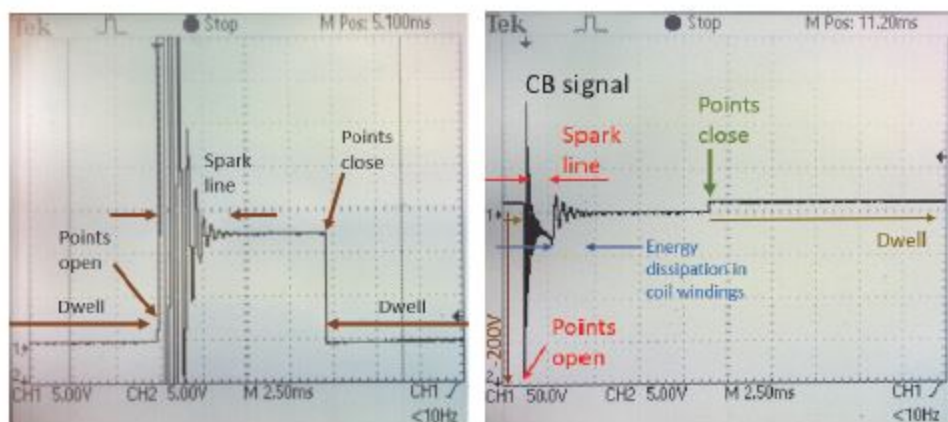


Fig. 4.2.3 Voltage waveform at the CB terminal while engine is running. (a) Negative earth configuration (b) Positive earth.

As far as igniting the fuel air mixture is concerned, it is the spark at the kick voltage that is the most important. The remaining spark during the spark line does not contribute significantly to combustion of the fuel.

It requires more voltage to initiate a spark at the spark plug than to maintain it since the gases in the spark plug gap have first to be ionised. Once ionised, the gases under dielectric breakdown and the voltage needed to maintain the spark is much reduced. The spark continues until there is no more ionised hydrocarbon gas present to sustain the spark current. The spark at the plug gap continues while the magnetic field diminishes and the oscillations due to the capacitor are reduced. The energy in the magnetic field appears as heat at the discharge at the spark plug gap. After the spark is extinguished, the remaining magnetic field dissipates and the potential at the CB terminal (and thus placed also across the capacitor) thus reduces. When the points finally close, a back emf is produced at the primary SW terminal opposing the battery voltage and the potential at the CB terminal goes negative before slowly rising to zero.

All this occurs over a small fraction of a second but can easily be seen on an oscilloscope. But a warning. An ordinary laboratory oscilloscope is usually not set up to handle hundreds of volts (the kick voltage) even though the coil might be powered by 12V, an automotive diagnostic oscilloscope which has the necessary capability to handle this input has to be used.

#### 4.2.3 Ballast Resistor

BMC cars (in Australia) are usually not fitted with ballast resistors that are seen on some inferior makes, but it is worth knowing what they are for. The ballast resistor is placed in series with the primary side of the coil. Its resistance changes with temperature (doubling or tripling its resistance from cold to hot). The resistor is often bypassed by the cranking circuit. What this ballast resistor does is to make the process of ignition more reliable when cranking a cold engine. In this system, the ignition coil is designed to work on about 8 to 10V. When the starter motor is engaged, the battery voltage drops to about 10 V, and so this is applied directly to the coil. The coil is designed to have an acceptable rate of current rise when 10V is applied to its primary. It does this by having a lower primary resistance in its windings. When cranking stops and the engine is running, the



As can be seen from Fig. 7.1.2, the roll centre may be above, at, or below ground level. When the vehicle rolls, the centre of mass shifts position, and the geometry of the linkages also change, and the roll centre thus also moves.

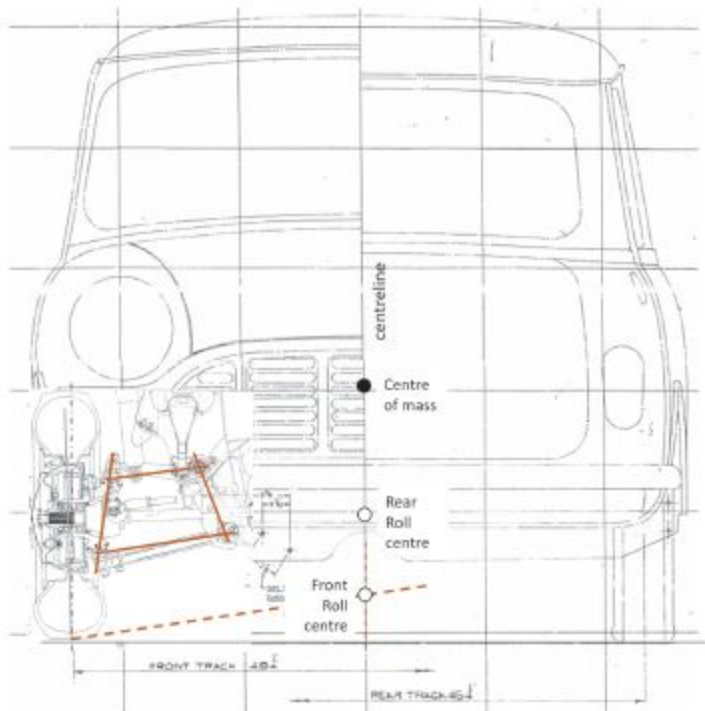
What then are the consequence of the roll centre location?

A low roll centre results in large roll angles. In this case, spring deflection may be excessive compared to suspension travel available and may result in bottoming or topping out against the bump stops. A low roll centre also results in a shift in the position of the centre of mass such that the reduction in force on the left hand side of Fig. 7.1.1 may reduce to zero (lifting of the inside front wheel, and so adversely affecting handling leading to understeer.

A high roll centre reduces the roll angle, but the wheels move sideways with consequent slip at the contact patch which adversely affects cornering.

Manufacturers usually design for a fairly low roll centre at the front and a higher one at the rear.

In a Morris Mini, the upper and lower arms are essentially parallel as shown in Fig. 7.1.3. The roll centre is found at the intersection of a line drawn parallel to the links, beginning at the centre of contact with the road, to the vehicle centreline. In this case, it can be seen that the roll centre is fairly low in relation to the centre of mass of the vehicle. The rear roll centre is drawn through the axis of the stub axles. As is usual custom, the front roll centre is lower than the rear roll centre.



**Fig. 7.1.3** Front suspension detail, Morris Mini.

The roll axis therefore looks like that shown in Fig. 7.1.4.